

Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application.

1. (canceled)
2. (currently amended) A walk-behind loader, which comprises:
 - (a) a frame having a front and a rear and at least one upright at the rear of the frame on one side of the frame, wherein the rear of the frame comprises a substantially planar, upwardly facing top wall that extends rearwardly and laterally relative to the frame with the top wall being located between opposite sides of the frame and with the top wall terminating at a rear edge;
 - (b) an internal combustion engine carried on the frame, wherein an engine hood or shroud is also carried on the frame;
 - (c) left and right endless drive tracks carried on the frame for propelling the frame in forward and reverse directions, the drive tracks being powered by the internal combustion engine;
 - (d) at least one loader arm pivotally connected to an upper end of the upright, wherein the loader arm extends forwardly and downwardly from the pivotal connection of the loader arm to the upright to terminate in a front end, the loader arm having a lowermost position in which the front end of the loader arm is generally adjacent the ground with the loader arm capable of being raised into elevated positions in which the front end of the loader arm is spaced further above the ground than in the lowermost position of the loader arm, wherein the loader arm is located beneath an upper portion of the engine hood or shroud when the loader arm is in its lowermost position;
 - (e) a ground grooming or working attachment pivotally connected to the front end of the loader arm;

(f) at least one actuator extending between the loader arm and the frame for pivoting the loader arm upwardly and downwardly relative to the frame about the pivotal connection of the loader arm to the frame;

(g) at least one actuator extending between the loader arm and the attachment for pivoting the attachment relative to the loader arm; and

(h) a control system positioned at the rear of the frame and comprising at least one control handle configured to be gripped and manipulated by a standing operator walking behind the frame during operation of the loader for controlling forward and reverse operation of the drive tracks, wherein the control system is located ~~sufficiently close to the rear of the frame~~ on the top wall at the rear of the frame forwardly of the rear edge of the top wall but without extending rearwardly past the rear edge of the top wall and the rear of the frame is configured to permit the standing operator walking behind the frame to be located substantially immediately behind the rear edge of the top wall while the standing operator grips the control system and to comfortably reach and operate the control system with the operator's arms being bent at the elbow.

3. (original) The walk-behind loader of claim 2, wherein a single upright and a single loader arm are provided on the frame.

4. (original) The walk-behind loader of claim 3, wherein the single upright and the single loader arm are provided on a left side of the frame.

5. (original) The walk-behind loader of claim 2, wherein a pair of uprights and a pair of loader arms are provided on the frame.

6. (canceled)

7. – 12. (canceled)